# Fast High-dimensional Kernel Summations Using the Monte Carlo Multipole Method

#### Problem

In this paper, we propose new computational techniques for efficiently approximating the following sum for each query point  $q_i \in \mathcal{Q}$ :

$$\Phi(q_i, \mathcal{R}) = \sum_{r_j \in \mathcal{R}} e^{-||q_i - r_j||^2/(2h^2)}$$
(1)

where  $\mathcal{R}$  is the reference set; each reference point is associated with a Gaussian function with a smoothing parameter h (the 'bandwidth'). This form of summation is ubiquitous in many statistical learning methods:

- Kernel density estimation
- Kernel regression
- Gaussian process regression
- Radial basis function networks
- Spectral clustering
- Support vector machines
- Kernel PCA

Cross-validation in all of these methods require evaluating Equation 1 for multiple values of h. Kernel density estimation, for example, requires  $|\mathcal{R}|$  density estimate based on  $|\mathcal{R}| - 1$ points, yielding a brute-force computational cost scaling quadratically (that is  $O(|\mathcal{R}|^2)$ ).

#### **Error Bounds**

Due to expensive computational cost, many algorithms approximate the Gaussian kernel sums at the expense of reduced precision, two of which is shown below:

**Definition 0.1.** An algorithm guarantees  $\epsilon$  **absolute error bound**, if for each exact value  $\Phi(q_i, \mathcal{R})$  for  $q_i \in \mathcal{Q}$ , it computes  $\left| \widetilde{\Phi}(q_i, \mathcal{R}) \text{ such that } \left| \widetilde{\Phi}(q_i, \mathcal{R}) - \Phi(q_i, \mathcal{R}) \right| \leq \epsilon. \right|$ 

**Definition 0.2.** An algorithm guarantees  $\epsilon$  relative error bound, *if for each exact value*  $\Phi(q_i, \mathcal{R})$  *for*  $q_i \in \mathcal{Q}$ *, it computes*  $\tilde{\Phi}(q_i, \mathcal{R}) \in \mathbb{R}$ | such that  $|\widetilde{\Phi}(q_i, \mathcal{R}) - \Phi(q_i, \mathcal{R})| \leq \epsilon |\Phi(q_i, \mathcal{R})|.$ 

#### **Our Contributions**

We propose a better Gaussian summation algorithm that overcomes the curse of dimensionality:

• Extends an earlier work [8] to guarantee "per-query" estimates using the following new error bound criterion:

**Definition 0.3.** An algorithm guarantees  $(1 - \alpha)$  probabilistic  $\epsilon$  relative error bound, if for each exact value  $\Phi(q_i, \mathcal{R})$  for  $q_i \in Q$ , it computes  $\Phi(q_i, \mathcal{R}) \in \mathbb{R}$ , such that with at least probability  $0 < 1 - \alpha < 1$ ,  $\left| \widetilde{\Phi}(q_i, \mathcal{R}) - \Phi(q_i, \mathcal{R}) \right| \le \epsilon \left| \Phi(q_i, \mathcal{R}) \right|$ .

- A new tree structure called *subspace tree* for reducing the computational cost of each distance computation inspired by an earlier work [11].
- Extensive experimental results up to 89 dimensional datasets for the first time.

### Algorithm

```
\mathsf{MCMM}(Q, R, \beta)
 if CANSUMMARIZEEXACT(Q, R, \epsilon)
   SUMMARIZEEXACT(Q, R)
 else if CANSUMMARIZEMC(Q, R, \epsilon, \beta)
   SUMMARIZEMC(Q, R, \epsilon, \beta)
 else
  if Q is a leaf node
     if R is a leaf node
      \mathsf{MCMMBASE}(Q, R)
     else
      \mathsf{MCMM}\left(Q, R^L, \frac{\beta}{2}\right), \mathsf{MCMM}\left(Q, R^R, \frac{\beta}{2}\right)
   else
     if R is a leaf node
       \mathsf{MCMM}(Q^L, R, \beta), \mathsf{MCMM}(Q^R, R, \beta)
     else
      MCMM \left(Q^L, R^L, \frac{\beta}{2}\right), MCMM \left(Q^L, R^R, \frac{\beta}{2}\right)
      \mathsf{MCMM}\left(Q^R, R^L, \frac{\beta}{2}\right), \mathsf{MCMM}\left(Q^R, R^R, \frac{\beta}{2}\right)
```

#### **Subspace Tree**

We use principal component analysis for building a subspace for each node.

- Leaf node: computed using PCABASE which can use the exact PCA [2] or a stochastic one [1].
- Internal node: the subspaces of the child nodes are approximately merged using the MERGESUBSPACES function [7].

#### $\mathsf{BUILDPCATREE}(\mathcal{P})$

if CANPARTITION( $\mathcal{P}$ )  $\{\mathcal{P}^L, \mathcal{P}^R\} \leftarrow \mathsf{PARTITIONSET}(\mathcal{P})$ 

- $N \leftarrow empty node$
- $N^{L} \leftarrow \mathsf{BUILDPCATREE}(\mathcal{P}^{L})$
- $N^R \leftarrow \mathsf{BUILDPCATREE}(\mathcal{P}^R)$
- $N.S \leftarrow \mathsf{MERGESUBSPACES}(N^L.S, N^R.S)$

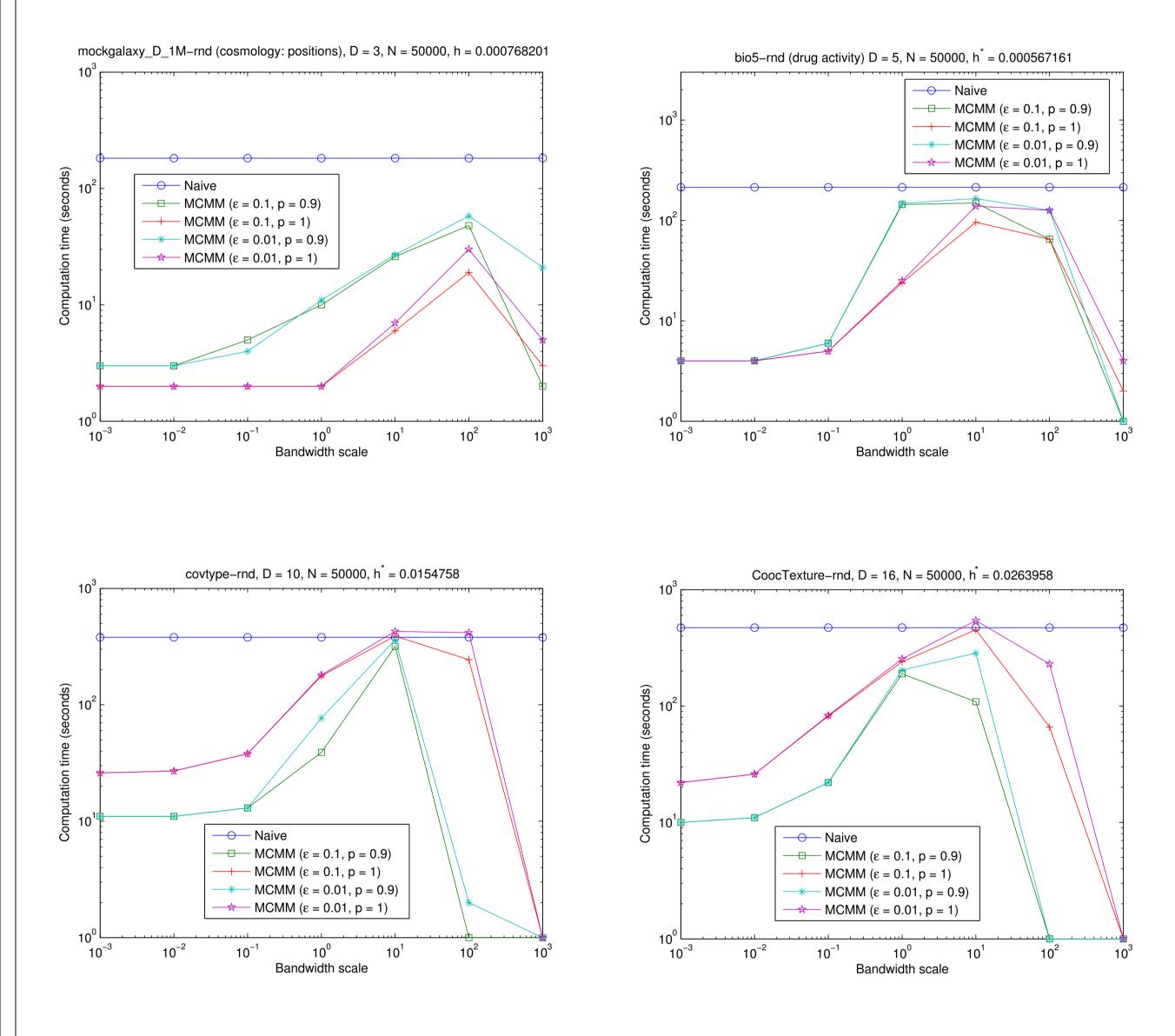
#### else

```
N \leftarrow \mathsf{BUILDPCATREEBASE}(\mathcal{P})
  N.S \leftarrow \mathsf{PCABASE}(\mathcal{P})
 N.\mathcal{P}_{proj} \leftarrow \mathsf{PROJECT}(\mathcal{P}, N.S)
return N
```

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### **Experimental Results and Conclusion**

We evaluated our algorithm <sup>a</sup> on six real-world datasets (scaled to fit in  $[0, 1]^D$  hypercube) for kernel density estimation at every query point with a range of bandwidths, from 3 orders of magnitude smaller than to three orders larger than optimal, according to the least-squares cross-validation score [12].



#### References

- 2003.
- 2000.

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• On low dimensional datasets (below 6 dimensions), the algorithm using series-expansion based bounds (MCMM) algorithm with p = 1 value) gives two to three times speedup compared to our approach that uses Monte Carlo sampling. • From 7 dimensions and beyond, our probabilistic algorithm (p = 0.9) consistently performs better than the algorithm using exact bounds by at least a factor of two.

• Our new method has the minimum time requirement for cross-validation over all bandwidth scales over the past work [3, 4, 6, 5, 10, 9]. We have already developed an improved version of our algorithm.

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<sup>a</sup>Times which include preprocessing costs are measured in CPU seconds on an AMD Opteron 3.0 GHz machine with 8 Gb of main memory and 1 Mb of CPU cache. All the codes that we have written and obtained are written in C and C++, and was compiled under -03 flags on Linux kernel 2.6.9. We have limited all datasets to 50K points.

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